

An End-to-end Large-area Tree Detection Approach on High Resolution Imagery Using Detection Transformer

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Object detection models in Deep Learning

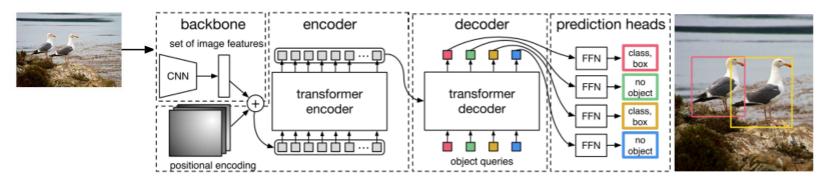
Convolutional Neural Networks

- RCNN, Fast RCNN, Faster RCNN, Mask RCNN
- YOLO and RetinaNet

Transformer

- Detection Transformer (DETR) (Carion 2020)
- Deformable DETR (Zhu 2020)
- DETR with Improved deNoising anchOr boxes (DINO) (Zhang 2022)

Overview of Detection Transformer architecture



Carion et al. 2020

Carion, N., Massa, F., Synnaeve, G., Usunier, N., Kirillov, A., Zagoruyko, S. (2020). End-to-End Object Detection with Transformers. In: Vedaldi, A., Bischof, H., Brox, T., Frahm, JM. (eds) Computer Vision – ECCV 2020. ECCV 2020.

Tree crown detection dataset and model training

Dataset labelling

- 330 WorldView-3 image patches (320×320)
- 23,643 tree crown bounding boxes





Tree crown detection dataset and model training

Dataset compiling

- COCO format
- Dataset spliting (300, 15, 15)

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"images": [{"id": 1, "width": 320, "height": 320,
           "file name": "tile WV3 2016-
11 north 106 0.tif"}],
"annotations": [{
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[[5.0, 158.5, 1.0, 157.5, 0, 155.0, 1.0, 148.5, 7.5,
150.0, 8.5, 156.0, 5.0, 158.5]],
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"category id": 1,
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Tree crown detection dataset and model training

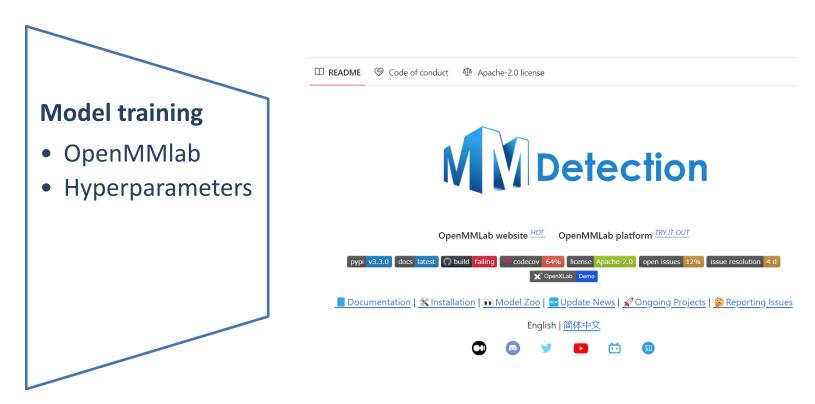
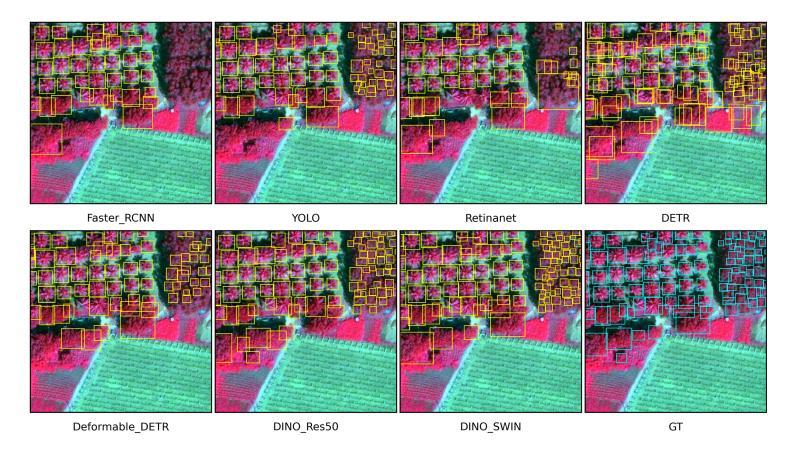


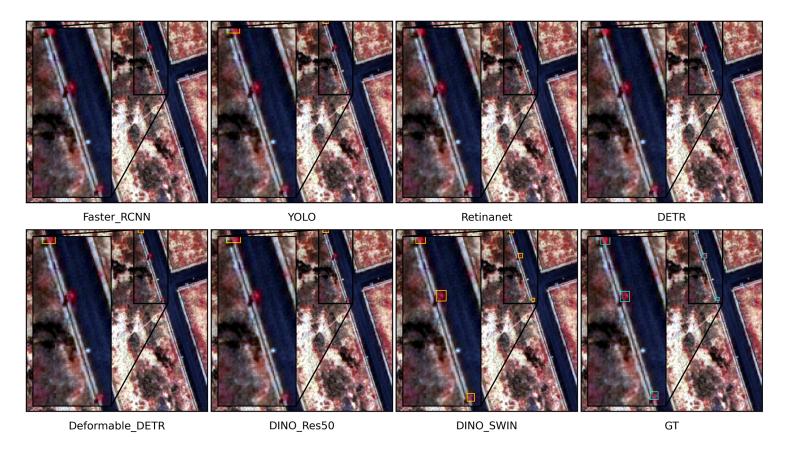
Table 3: Summary of detection models' performance computed based on the test dataset.

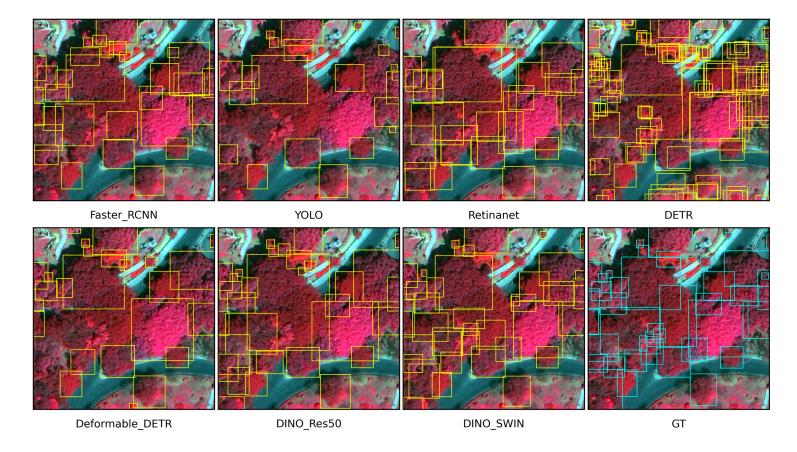
Detection models	\mathbf{DT}	GT	TP	FP	DR(%)	Precision(%)	Recall(%)	F1(%)	AP(%)
Faster RCNN	318	916	243	75	35	76	27	39	28
YOLO	649	916	462	187	71	71	50	59	56
RetinaNet	562	916	191	371	61	34	21	26	19
DETR	1284	916	182	1102	140	14	20	17	5
Deformable-DETR	594	916	381	213	65	64	42	50	41
DINO-Res50	810	916	563	247	88	70	61	65	60
DINO-SWIN	871	916	663	208	95	76	72	(74)	(76)

Note: DT (detections), GT (ground truths), TP (true positives), FP (false positives), DR (detection rate) and AP (average precision).



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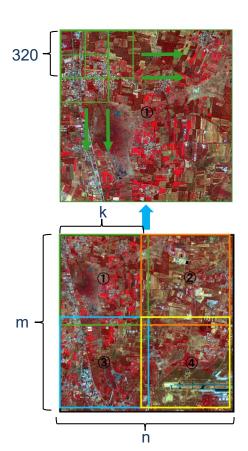


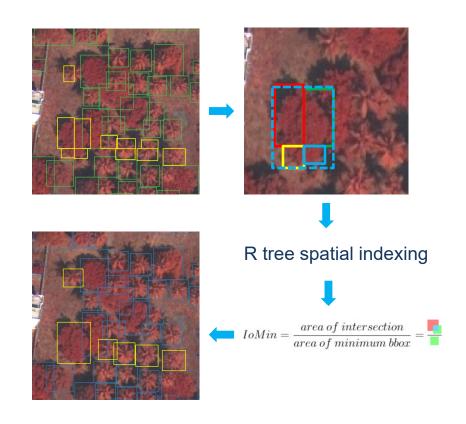


Large-area tree detection approach consists of two steps

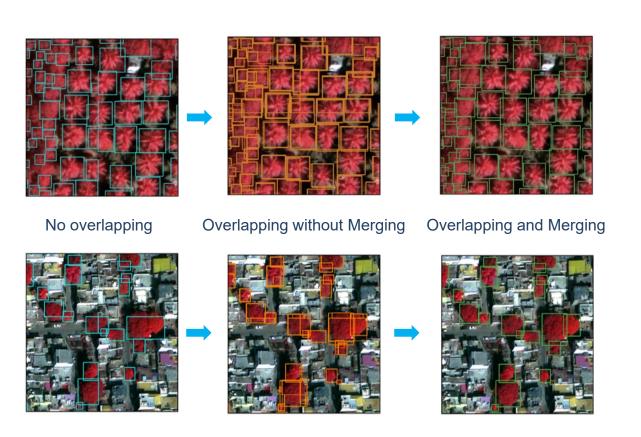
Step 1: two-level partitioning scheme

Step 2: R-tree based Box Merging





More examples of detection results using proposed approach

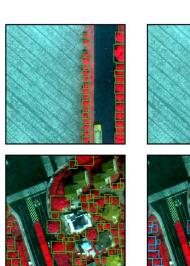


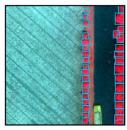


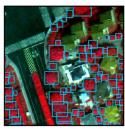
Bengaluru (250 km²) ~1.3 million trees
Precision: 76%
Recall: 72%

F1 score: 74%

Proposed approach tested on two additional locations













Shanghai (26 km²) ~90k trees Precision: 76% Recall: 70%

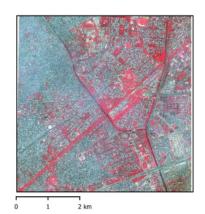
F1 score: 73%

Detections

Ground truth

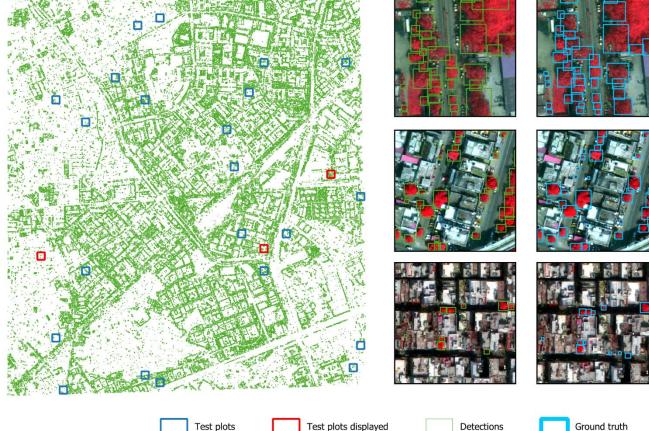
Test plots

Proposed approach tested on two additional locations



Delhi (26 km²**)** ~70k trees Precision: 86% Recall: 87%

F1 score: 87%



An End-to-end Large-area Tree Detection Approach on High **Resolution Imagery Using Detection Transformer**

- a) We explored the potential of detection transformer (DETR) models on identifying individual tree from high resolution satellite imagery.
- We devised an end-to-end tree detection approach utilizing DINO as classifier, incorporating two-level partitioning scheme, and employing a R-tree based Box Merging technique.
- The proposed tree detection approach has been further tested on two additional locations with different image quality, showing its strong applicability.









